Technology-supported exercise therapy for patients with chronic nonspecific low back pain: a feasibility study



Thomas Matheve¹, Guido Claes², Enzo Olivieri², Annick Timmermans¹

¹Rehabilitation Research Center (REVAL), Biomed, Faculty of Medicine and Life Sciences, Hasselt University, Belgium; ²Department of physical and rehabilitation medicine, Jessa hospital, Belgium.

Background & Aims

Various technological systems supporting exercise therapy for low back pain (LBP) have been developed in recent years. The current technology-supported exercise therapy programs for LBP mostly adopt an analytical approach and do not offer technological support at home [1]. However, there is growing consensus that exercise programs should be tailored to the patient's specific needs. To improve the additional benefit of technological support, it seems crucial that technological systems can be integrated in this individual and functional approach. The *aims* of this study are:

1. To develop a functional (home) exercise program compatible with technological support.

2. To assess the feasibility and clinical outcome of this program

Table 1. Different phases of program with indication of availability of technological support

Week 1-3	Week 4-5	Week 6-13	Week 14-18
Standard rehabilitation	Familiarization period	Technological support hospital	Weaning-off period
No technological support	Technological support at hospital	Technological support home	Standard rehabilitation



Methods

Subjects

Inclusion

Chronic non-specific low back pain

Diagnosis of a motor control impairment

Age 18-65 years old

Exclusion

Signs or symptoms of nerve root involvement Underlying serious pathology Pregnancy or <1 year post-partum Known allergy to tape

Technological system

The ValedoMotion[®] system (version 1.2, Hocoma, Switzerland) is a rehabilitation tool for patients with LBP. It consists of a laptop, a remote control and three inertial wireless motion tracking sensors. Two of the sensors are placed at the L1 and S1 level (Fig. 1), while one sensor is used for the calibration of the system. The sensor signals are sent to the laptop via which the patient can practice pelvic tilt exercises using serious games (Figs. 2A-C), and receive visual and auditory feedback about exercise performance with the 'target application' (Fig. 2D). The visual feedback is displayed as a bull's eye with colored concentric circles. The cursor on the screen can be placed in the middle of the bull's eye to register the neutral position. The system uses the movement of the S1-sensor relative to the L1-sensor to control the games. In this way, the patient has to dissociate pelvic movements (S1) from the upper lumbar spine (L1) and the thoracic spine. The serious gaming was used for thoracolumbar dissociation exercises, while the target application was used to support functional motor control exercises.

Fig. 4. Example of motor control retraining for a motor control problem towards extension. **4A-B**. Correct performance. **4C**. Incorrect performance with excessive lumbar extension. **4D**. Integration of real life objects.

Results

Table 2. Sociodemographic data (n = 10)

	Median	Interquartile range
Age (years)	35.5	28.3
Duration low back pain (years)	8.5	17.6
BMI (kg/m²)	22.6	2.1
Gender (male/female)	8/2	

Table 3. Results for clinical an	nd patients' a	cceptance out	comes (n=10)			
	ТО	T1	T2	Т3	Τ4	P-value
Clinical outcome measures						



Fig. 1. Sensor placement.

Figs. 2A-C. Serious games for improving thoracolumbar dissociation. Fig. 2D: Target game providing postural feedback

Intervention

A tailored exercise program consisting of 36 partially supervised 2-hour sessions (18 weeks, 2x/week) at an outpatient rehabilitation center. Each session consisted of 30' of general reconditioning and 90' of individually tailored functional motor control exercises (Fig. 3). The motor control exercises were partially supported by postural feedback with the ValedoMotion, both in a hospital setting and at home (Table 1).

NPRS (/10)	5.5 (4.0)	-	3.5 (2.8)	-	2.5 (2.5) ^a	0.011
RMQ (/24)	9.5 (5.5)	-	4 (4.5) ^a	-	4 (5.0) ^a	0.004
PSFS (/10)	4.7 (1.1)	-	6.8 (3.7) ^a	-	7.8 (3.5) ^{a,b}	< 0.001
TSK (17-68)	36.5 (15)	-	31 (12.8)	-	33 (10.5)	0.009
PSEQ (/60)	40 (16.5)	-	51 (12.25)	-	54 (12) ^a	0.002
Short form 36						
Physical component	36.4 (9.2)	-	49.5 (11.7) ^a	-	50.1 (11.6) ^a	<0.001
Mental component	58.1 (9.0)	-	57.9 (6.7)	-	58.6 (6.8)	0.5
Sick leave (yes/no)	2/6	-	1/7	-	0/8	0.22
Outcome measures related	to patients' ac	ceptance				
CEQ (3-27)*						
Credibility	21.5 (5.5)	22.0 (2.8)	23.0 (5.8)	23.0 (5.8)	-	0.63
Expectancy	17.4 (7.3)	20.5 (4.9)	19.7 (5.2)	19.7 (5.4)	-	0.4
IMI (3-27)*						
Interest/enjoyment	4.6 (1.6)	4.9 (1.8)	4.9 (1.7)	5.4 (1.8)	-	0.19
Competence	3.9 (1.5)	4.5 (2.2)	5.1 (1.4) ^c	5.3 (1.5) ^c	-	0.001
Effort/importance	5.7 (1.6)	5.7 (1.6)	5.9 (1.6)	5.3 (1.2)	-	0.39
Pressure/tension	5.0 (1.4)	5.4 (0.6)	6.4 (1.5) ^c	6.0 (0.6) ^c	-	0.002
Value/usefulness	5.9 (1.3)	5.9 (0.7)	6.1 (1.2)	5.9 (1.0)	-	0.34
Relatedness	5.3 (1.3)	5.8 (0.9)	6.0 (0.8)	5.4 (1.2)	-	0.079
Satisfaction (/10)	-	7.0 (1.5)	8.0 (1.5)	8.5 (3.5)	8 (3)	0.51
Adherence (1-36)	-	-	_	-	36 (2.5)	

Data are denoted as median scores (interquartile range), except for the outcome sick leave. The *p*-values are for comparisons between more than two test occasions. CEQ= credibility and expectancy questionnaire, IMI= intrinsic motivation inventory, NPRS= numeric pain rating scale, RMQ= Roland Morris Questionnaire, PSFS= patient specific functioning scale, TSK= Tampa scale for kinesiophobia, PSEQ= pain self-efficacy questionnaire, Satisfaction= patient satisfaction with the treatment. *Baseline scores were obtained after the first session.

a= significant difference compared to baseline (p< 0.017), b= significant difference compared to T2 (p< 0.017), c= significant difference compared to baseline (p< 0.0125). T0 = baseline, T1 = end week 3, T2 = end week 8, T3 = end week 13, T4 = end week 18.



Fig. 3. Schematic presentation of intervention

Discussion & conclusions

- It seems feasible to support functional motor control exercises with sensor based postural feedback, both in a supervised as in a home environment.
- Patients found the exercise program credible and remained motivated for the full duration of the treatment. Further, the technology-supported exercise program led to clinically significant improvements in various outcomes.
- Results should be interpreted with care because of the small number of participants.
- Explaining and demonstrating the technological system to the participants took about 20-30 minutes. This might be a barrier to use it in daily clinical practice where patients receive less treatments.
- Future trials should assess the additional value of postural feedback to regular therapy, costeffectiveness and time-efficiency of technological systems.

References

[1] Matheve T, Brumagne S, Timmermans AA. Am J Phys Med Rehabil. 2016 Aug 31